

3A, 40V Asynchronous Step-Down Converter

## DESCRIPTION

The XR5116F is a current mode monolithic buck switching regulator. Operating with an input range of 4.7-40V, the XR5116F delivers 3A of continuous output current with an integrated high side N-Channel MOSFET. At light loads, XR5116F operates in low frequency to maintain high efficiency and low output voltage ripple. Current mode control provides tight load transient response and cycle-by-cycle current limiting.

The XR5116F guarantees robustness with input under-voltage lockout, start-up current run-away protection, output short protection and thermal protection.

The XR5116F is available in SOP8 and ESOP8 package, which provides a compact solution with minimal external components.

### **FEATURES**

- 4.7V to 40V operating input range 3A output current
- Up to 92% efficiency
- High efficiency (>78%) at light load
- Internal soft-start
- Adjustable switch frequency
- Input under-voltage lockout
- Start-up current run-away protection
- Output short protection
- Thermal protection
- Available in SOP8 and ESOP8 package

### APPLICATIONS

- Distributed Power Systems
- Networking Systems
- FPGA, DSP, ASIC Power Supplies
- Green Electronics/ Appliances
- Notebook Computers

### **TYPICAL APPLICATION**





# **ORDER INFORMATION**

DEVICE <sup>1)</sup>	PACKAGE	TOP MARKING <sup>2)</sup>	
XR5116FSOPB#TRPBF	SOP8	XR5116F YWLLL	
XR5116FESOP#TRPBF	ESOP8	XR5116F YWLLL	

Notes:



# **PIN CONFIGURATION**



# ABSOLUTE MAXIMUM RATING<sup>1)</sup>

VIN, EN, SW Pin .	-0.3V to 45V
BST Pin . SW-0.3V to	SW+5V
All other pins .	-0.3V to 6V
Junction Temperature <sup>2) 3)</sup> .	150ºC
Lead Temperature .	260°C
Storage Temperature .	-65°C to +150°C



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# **RECOMMENDED OPERATING CONDITIONS**

Input Voltage VIN	
Output voltage Vout	
Operating Junction Temp.	-40°C to 125°C

# THERMAL PERFORMANCE<sup>4)</sup>

SOP8	<b>3</b> ,	.45°C/W
ESOP8	)	.10ºC/W

#### Note:

1) Exceeding these ratings may damage the device.

2) The XR5116F guarantees robust performance from -40°C to 150°C junction temperature. The junction temperature range specification is assured by design, characterization and correlation with statistical process controls.

- 3) The XR5116F includes thermal protection that is intended to protect the device in overload conditions. Thermal protection is active when junction temperature exceeds the maximum operating junction temperature. Continuous operation over the specified absolute maximum operating junction temperature may damage the device.
- 4) Measured on JESD51-7, 4-layer PCB.

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# **ELECTRICAL CHARACTERISTICS**

Item	Symbol	Condition	Min.	Тур.	Max.	Units
V <sub>IN</sub> Under-voltage Lockout Threshold	Vin_min	V <sub>IN</sub> falling	3.5	3.8	4.1	V
V <sub>IN</sub> Under-voltage Lockout Hysteresis <sup>5)</sup>	Vin_min_hyst	V <sub>IN</sub> rising		400		mV
Shutdown Supply Current	I <sub>SD</sub>	V <sub>EN</sub> =0V		1.6	5	μA
Supply Current	lq	$V_{EN}$ =5V, $V_{FB}$ =1.2V		65	100	μA
Feedback Voltage	V <sub>FB</sub>	4.7V <v<sub>VIN&lt;40V</v<sub>	0.780	0.8	0.820	V
Top Switch Resistance <sup>5)</sup>	R <sub>DS(ON)T</sub>			63	78	mΩ
Top Switch Leakage Current	I <sub>LEAK_TOP</sub>	V <sub>IN</sub> =40V, V <sub>EN</sub> =0V, V <sub>SW</sub> =0V			1	uA
Top Switch Current Limit <sup>5)</sup>	I <sub>LIM_TOP</sub>	Minimum Duty Cycle	3.6	4.5		А
Error Amp Min Source Current		FB=0.4V		15		uA
Error Amp Min Sink Current		FB=1.2V		-15		uA
Switch Frequency	Fsw	R <sub>RT</sub> = 260k	100	160	220	kHz
Minimum On Time <sup>5)</sup>	T <sub>ON_MIN</sub>			120		ns
Minimum Off Time	T <sub>OFF_MIN</sub>	V <sub>FB</sub> =0V		150		ns
EN Shutdown Threshold	V <sub>EN_TH</sub>	V <sub>EN</sub> rising, FB=1V	1.0	1.3	1.6	V
EN shut down hysteresis <sup>5)</sup>	V <sub>EN_HYST</sub>	V <sub>EN</sub> rising, FB=1V		100		mV
Thermal Shutdown <sup>5)</sup>	T <sub>TSD</sub>			137		°C
Thermal Shutdown Recovery Hysteresis <sup>5)</sup>	T <sub>TSDR</sub>			15		°C

**Note:** 5) Guaranteed by design.



# **PIN DESCRIPTION**

PIN SOP8	PIN ESOP8	Name	Description	
1	1	CIM	SW is the switching node that supplies power to the output. Connect the output LC	
		300	filter from SW to the output load.	
2	2	EN	Drive EN pin high to turn on the regulator and low to turn off the regulator.	
			Compensation pin. Comp is used to compensate the regulation control loop. Connect a series RC network from COMP to GND to compensate the regulation	
3	3	COMP	control loop. One ceramic cap such as several tens pF is usually connected from	
			COMP to GND to decouple the voltage noise.	
4	4	FB	Output feedback pin. FB senses the output voltage and is regulated by the control	
4			loop to FB reference voltage 0.8V. Connect a resistive divider at FB.	
5	5/ EP	GND	Ground.	
6	6	PT	Voltage at the RT pin is regulated at 1.2V. Switch frequency of the regulator can be	
0	0		adjusted by connecting a resistor at the RT pin to ground.	
		7 VIN	Input voltage pin. VIN supplies power to the IC. Connect a 4.7V to 40V supply to	
7	7		VIN and bypass VIN to GND with a suitably large capacitor to eliminate noise on	
			the input pin to the IC.	
			Bootstrap pin for top switch. A 0.1uF or larger capacitor should be connected	
8	8	BST	between this pin and SW pin to supply current to the top switch and top switch	
			driver.	

# **BLOCK DIAGRAM**





# FUNCTIONAL DESCRIPTION

The XR5116F is an asynchronous, current-mode, step-down regulator. It regulates input voltages from 4.7V to 40V down to an output voltage as low as 0.8V, and is capable of supplying up to 3A of load current.

### **Current-Mode Control**

The XR5116F utilizes current-mode control to regulate the output voltage. The output voltage is measured at the FB pin through a resistive divider and the error is amplified by the internal transconductance error amplifier. The output of internal error amplifier is compared to the switch current measured internally to control the output current limit.

### **PFM Mode**

The XR5116F operates in PFM mode at light load. In PFM mode, switch frequency is continuously controlled in proportion to the load current, i.e. switch frequency is decreased when load current drops to boost power efficiency at light load by reducing switch-loss, while switch frequency is increased when load current rises, minimizing both load current and output voltage ripples.

### **Power Switch**

An N-Channel MOSFET switch is integrated on the XR5116F to down convert the input voltage to the regulated output voltage. Since the top MOSFET needs a gate voltage great than the input voltage, a boost capacitor connected between BST and SW pins is required to drive the gate of the top switch. The boost capacitor is charged by the internal 3.3V rail when SW is low.

### VIN Under-Voltage Protection

XR5116F can regulate a wide range input voltage down to an output voltage. If the input voltage decreases to under voltage lockout threshold, the regulator enters into UVLO protection to shutdown internal logic and function blocks.

### **Enable Pin**

EN pin is a analog control pin that turns the regulator on and off. Drive EN pin high to turn on the regulator and drive it low to turn it off. A resistor such as  $100K\Omega$  can be connected between EN pin and VIN pin for automatic startup.

### **COMP** Voltage

The current limit is decided by the maximum comp voltage which is around 2.5V. Comp voltage is also adjusted with the output current. The comp voltage decreases as load current drop. When comp voltage keeps the maximum value for around 12480 cycle, the over load protection is triggered. IC enters into the hiccup mode during the OLP.

### **Output Current Run-Away Protection**

At start-up, due to the high voltage at input and low voltage at output, current inertia of output inductance can be easily built up, resulting in a large start-up output current. COMP value is limited and rise up slowly for a period of time when start up. By such control mechanism, the output current at start-up is well controlled.

### **Output Short Protection**

When the output is shorted to ground, output current rapidly rises and if it hits the OCP (over



current protection) limit, which is 1.3A above the normal peak current limit, switch frequency is halved to allow time for the inductor current to fall to a safe level. If the OCP limit is hit again in the next cycle, switch frequency is halved again. In the extreme case, switch frequency can be decreased to 1/128 of the original frequency set by the resistor at the RT pin.

### Thermal Protection

When XR5116F inner temperature rises above the Over Temperature Protection threshold, it is forced into thermal shut-down. Only when IC inner temperature drops below Over Temperature Recovery threshold can the regulator becomes active again.



### **APPLICATION INFORMATION**

#### Setting the Output Voltage

The output voltage is set using a resistive divider from the output voltage to FB pin as Figure 1. The voltage divider divides the output voltage down to the feedback voltage by the ratio:



Figure 1: Output Voltage Setup

Where  $V_{\text{FB}}$  is the feedback voltage and  $V_{\text{OUT}}$  is the output voltage.

The output voltage is:

$$V_{OUT} = V_{FB} \cdot \frac{R2 + R5}{R2}$$

V<sub>FB</sub> is 0.8V reference. R2 can be as high as 100KΩ, but a typical value is 10 KΩ~20 KΩ. For example, R2 is 22 KΩ, R5 is determined by:

$$R5 = 27.5 \times (V_{OUT} - 0.8) (K\Omega)$$

### **Operating Frequency**

XR5116F working frequency can be adjusted in different application. Set the resistor connected to RT pin to setup the working frequency as Figure 2 and following expression.

$$f_{s} = \frac{1}{22.77 \times 10^{-12}.R_{4} + 0.315 \times 10^{-6}} Hz$$



Figure 2: Operating Frequency Setup

#### **EN Function**

EN pin is a analog input that turns the regulator ON or OFF. Drive EN pin high to turn on the regulator and drive it low to turn off regulator.

Usually, pull up with  $100K\Omega(R1)$  resistor for automatic startup (R6=NC).

Low input voltage protection can be setup through EN pin to adjust the R1 and R6 as Figure 3. EN pin voltage below 1.2V to turn off XR5116F when low input voltage.



Figure 3: Input Voltage UVLO Setup For example, Vin=12V, setup the Vin=10V to trigger the low input voltage protection. So, R1 and R6 can be configured as R1=1M $\Omega$ and R6=136.3K $\Omega$ .

### **BST Capacitor**

BST cap supplies the drive for the high-side N-MOSFE switch, connected from the BST pin to SW pin as Figure 4.



Figure 4: BST Cap

The BST cap is charged by the internal 3.3V rail when SW is low. Usually, one ceramic cap 0.1uF or greater capacitor is ok for high side MOS driver.

#### **Compensation Loop**

COMP is used to compensate the regulation control loop for system stability and transient response. Connect a series RC network



(Pole-zero combination) from COMP to GND to optimize the control loop as Figure 5.



Figure 5: Compensation Loop

In some cases, an additional ceramic capacitor (C5 such as 47pF) from COMP to GND is required to eliminate the high frequency noise influence.

Normally application with 5V/3.3V output, 12V/24V input, the below table parameter is recommended.

R3 (KΩ)	C4 (pF)	C5 (pF)		
50 ~200	330~1500	NC/22~100		

### **Power Inductor**

The inductor is required to supply constant current to the output load. A larger value inductor results in less current ripple and also lower output ripple. However, the larger value inductor has a larger physical size, bigger series resistance, high cost or lower saturation current. A good rule to determining the inductance is to allow the peak-to-peak ripple current in the inductor.

It's recommended to allow inductor ripple current  $\triangle I_{PP}$  of 30% maximum peak current. So we can get the proper inductor value as follow.

$$L = \frac{V_{OUT}}{f_S \cdot \Delta I_{PP}} \cdot \left(1 - \frac{V_{OUT}}{V_{IN}}\right)$$

Where  $V_{OUT}$  is output voltage,  $V_{IN}$  is input voltage,  $f_S$  is switching frequency and  $\triangle I_{PP}$  is the peak-to-peak inductor ripple current.

Choose an inductor that will not be saturate under the maximum inductor peak current. The peak inductor current can be calculated by following expression:

$$I_{LP} = I_{OUT} + \frac{V_{OUT}}{2 \cdot f_S \cdot L} \cdot \left(1 - \frac{V_{OUT}}{V_{IN}}\right)$$

Where  $I_{OUT}$  is the load current.

### **Freewheel Diode**

Freewheel diode supply the current route when high side MOS turns off. The system efficiency is worse if the forward voltage drop is high. So, this diode is recommended to use the schottky diode with lower forward voltage drop to improve overall efficiency.

For example, the B540 (5A/40V) schottky diode performs well in application.

### **Input Capacitor**

Use low ESR capacitors for the best performance. Ceramic capacitors are preferred, but tantalum or low-ESR electrolytic capacitors may also suffice. It's recommended to choose X5R or X7R dielectrics when using ceramic capacitors.

The RMS current in the input capacitor can be estimated by following expression:

$$I_{C1} = I_{OUT} * \sqrt{\frac{V_{OUT}}{V_{IN}} * \left(1 - \frac{V_{OUT}}{V_{IN}}\right)}$$

Choose the input capacitor whose RMS current rating greater than  $I_{C1}$ .

Input voltage ripple for low ESR capacitors can be estimated as follow:

$$\Delta V_{IN} = \frac{I_{OUT}}{f_{S} * C_{1}} * \frac{V_{OUT}}{V_{IN}} * \left(1 - \frac{V_{OUT}}{V_{IN}}\right)$$

It should increase the input capacitor if the input voltage ripple is big. Besides, one ceramic cap such as 0.1uF is suggested to be placed as close to the IC as possible.

### **Output Capacitor**

The output capacitor is required to maintain the DC output voltage. The output voltage ripple can be estimated by following.



$$\Delta V_{OUT} = \frac{V_{OUT}}{f_{S} * L} * \left(1 - \frac{V_{OUT}}{V_{IN}}\right) * \left(R_{ESR} + \frac{1}{8 * f_{S} * C_{3}}\right)$$

Where  $C_3$  is the output capacitance value and  $R_{\text{ESR}}$  is the equivalent series resistance (ESR) value of the output capacitor.

Ceramic, tantalum, or low ESR electrolytic capacitors are recommended. Low ESR capacitors are preferred to keep the output voltage ripple low.



# PCB LAYOUT

PCB layout is very important to achieve stable operation. It is highly recommended to duplicate EVB layout as follow these guidelines.

- Keep the path of switching current short and minimize the loop area formed by input cap, high-side MOSFET and freewheel diode.
- 2. Bypass ceramic capacitors are suggested to be put close to the Vin Pin.
- 3. Ensure all feedback connections are short and direct. Place the feedback

resistors and compensation components as close to the chip as possible.

- 4. Route SW away from sensitive analog areas such as FB.
- Connect VIN, SW, and especially GND respectively to a large copper area to cool the chip to improve thermal performance and long-term reliability. The 2os copper thickness is suggested for better thermal performance in real application.

Figure 6 is the PCB layout reference.



Figure 6: PCB Layout Reference



# **REFERENCE DESIGN**

#### **Reference 1:**

Vin: 8V~36V Vout: 5V Iout: 0~3A



#### Reference 2:

Vin: 5V~36V Vout: 3.3V Iout: 0~3A





# PACKAGE OUTLINE





